

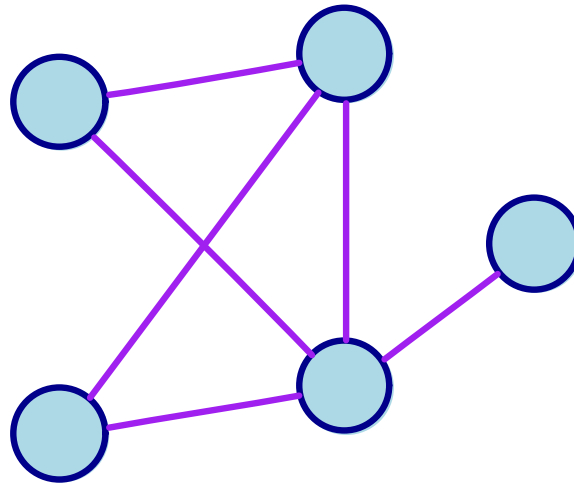


Graphs



A **graph** is

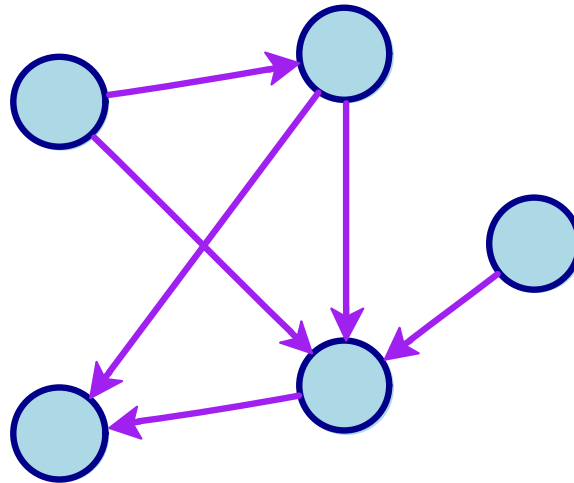
- a set of **nodes** 
- a set of **edges** 
each connecting two nodes



Graphs

A **directed graph** is

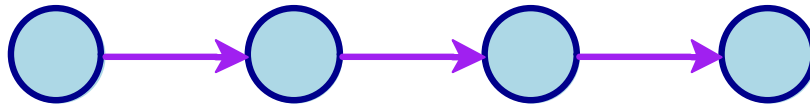
- a set of **nodes** 
- a set of **edges** 
each connecting one node to another node



We'll just use “graph” to mean “directed graph”

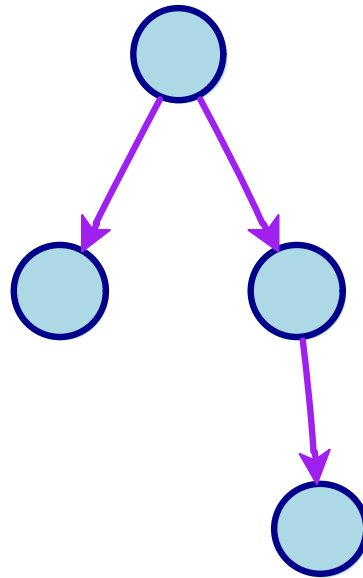
Graphs: Lists

At most one outgoing edge \Rightarrow ***list***



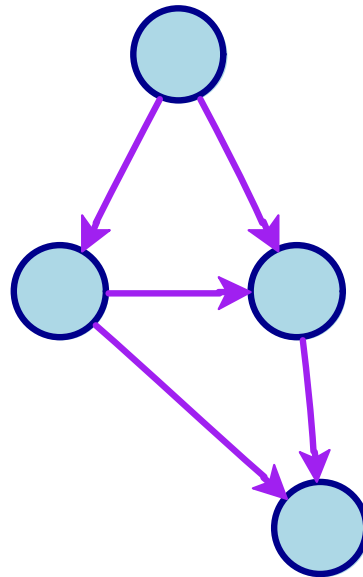
Graphs: Trees

Reach each node in only one way \Rightarrow **tree**



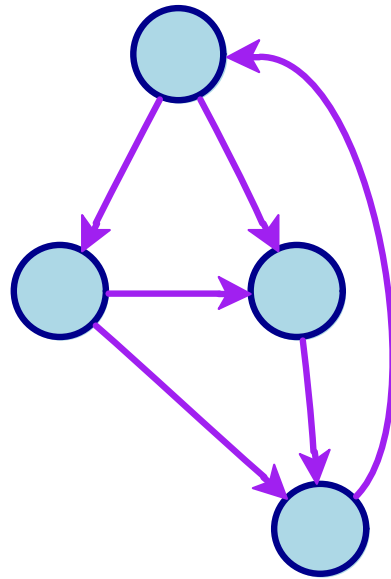
Graphs: DAG

Can't get to a node from itself \Rightarrow
directed acyclic graph (DAG)



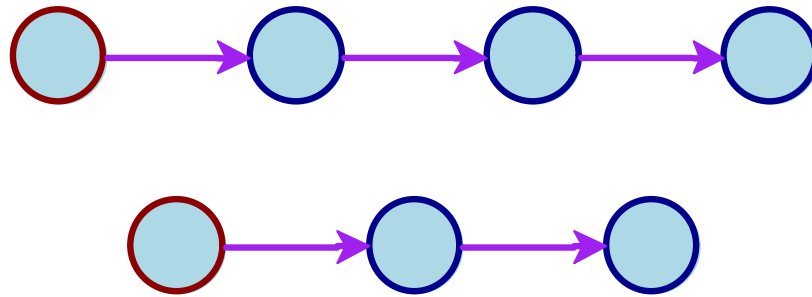
Graphs: Cycles

Can get to a node from itself \Rightarrow **graph**



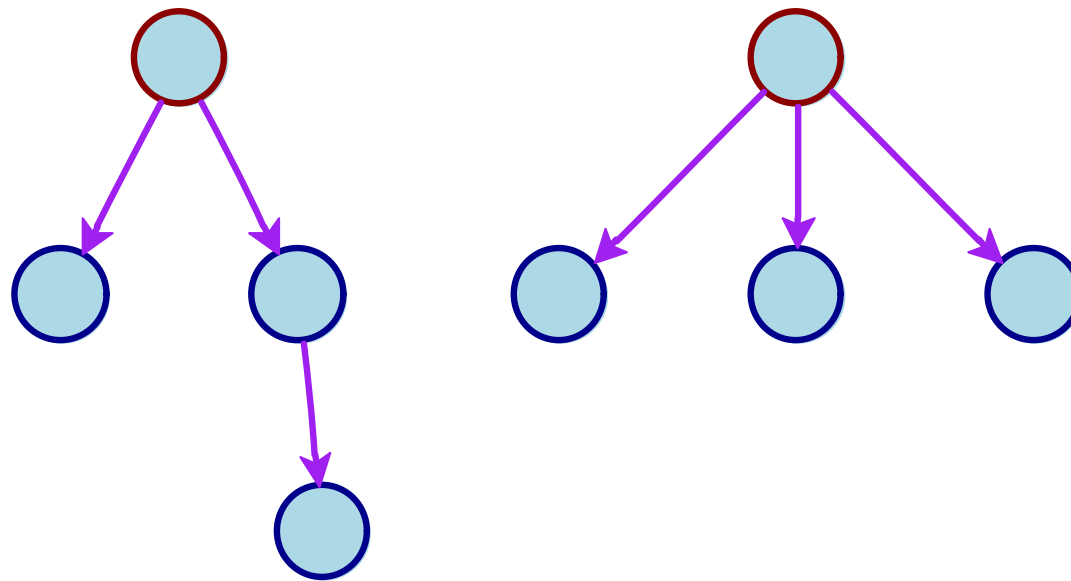
Roots

Some nodes might be considered **roots** — often nodes that reach all others



Roots

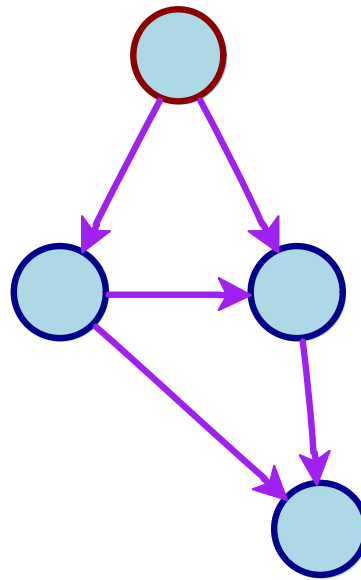
Some nodes might be considered **roots** — often nodes that reach all others



A graph containing only trees is a **forest**

Roots

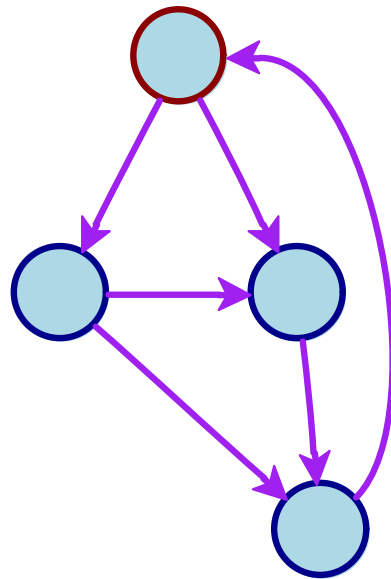
Some nodes might be considered **roots** — often nodes that reach all others



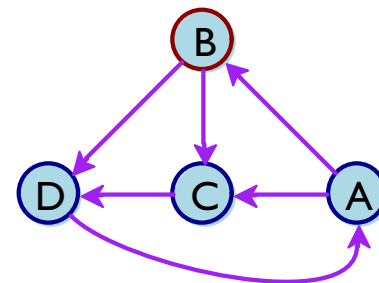
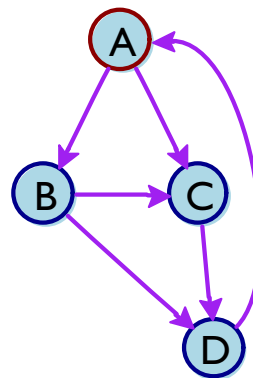
Can reach all nodes from some root \Rightarrow a **connected** graph

Roots

Some nodes might be considered **roots** — often nodes that reach all others



Multiple candidate roots:



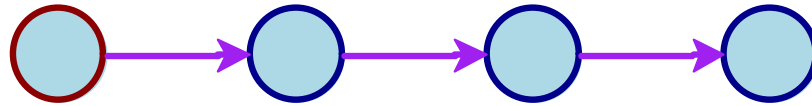
Representing Graphs

Graphs can be represented in different ways:

- Nodes as structs/objects, edges as pointers/references
- Nodes as objects, edges in a dictionary
- Nodes as integers, edges as a list of pairs of numbers

Unless you're solving abstract graph problems, typically you have an existing data definition that you might think of as a graph — probably matching the first case

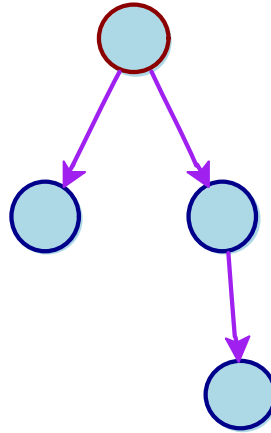
Designing Programs: Lists



```
(define (F n)
  (cond
    [(empty? n) ...]
    [else ... (F (rest n)) ...]))
```

```
for (n = root;
     n != NULL;
     n = n->next) {
  ....
}
```

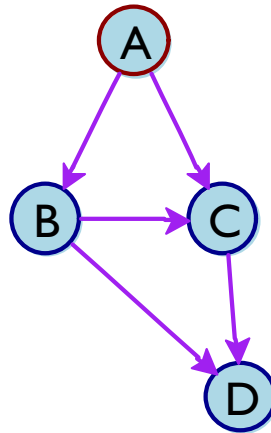
Designing Programs: Trees



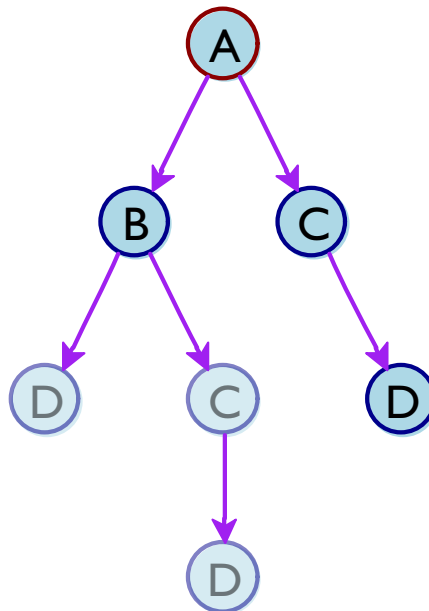
```
(define (F n)
  (cond
    [(empty? n) ...]
    [else ... (F (child1 n))
               ... (F (childN n)) ...]))
```

- Depth-first vs. breadth-first
- Might express recursion through a stack or queue

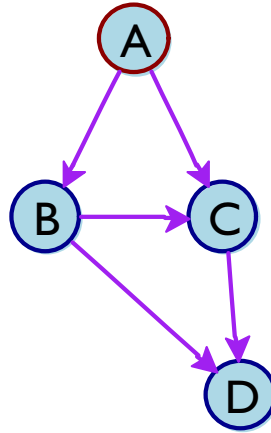
Designing Programs: DAGs



- Sometimes, treat a DAG as a tree

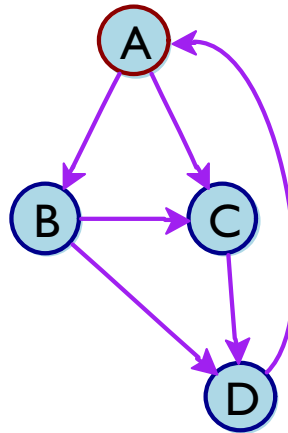


Designing Programs: DAGs



- Sometimes, treat a DAG as a graph...

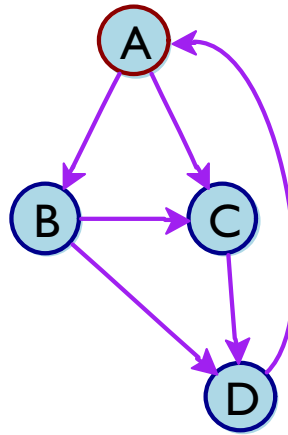
Designing Programs: Graphs



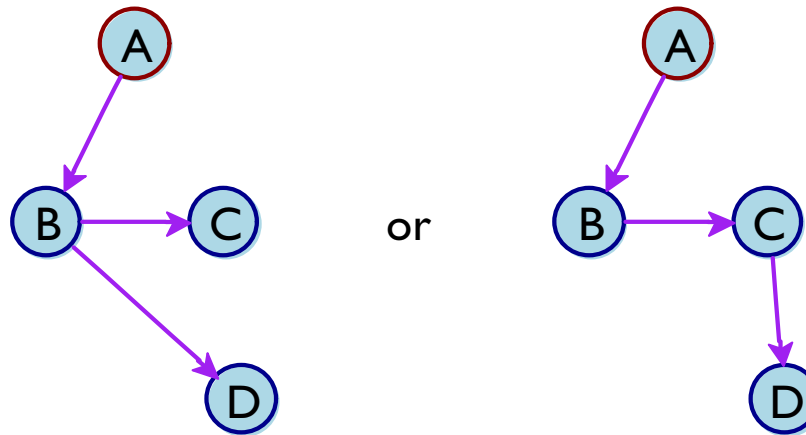
Like a tree, but accumulate seen

```
(define (F n)
  (cond
    [(seen? n) ...]
    [else (seen! n)
          (cond
            [(empty? n) ...]
            [else ... (F (child1 n))
                      ... (F (childN n)) ...])]))
```

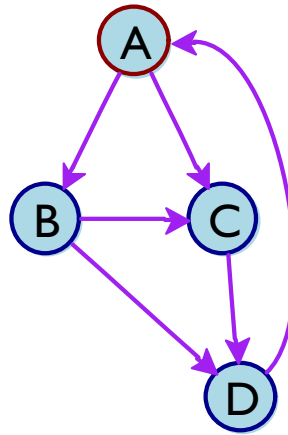

Designing Programs: Graphs



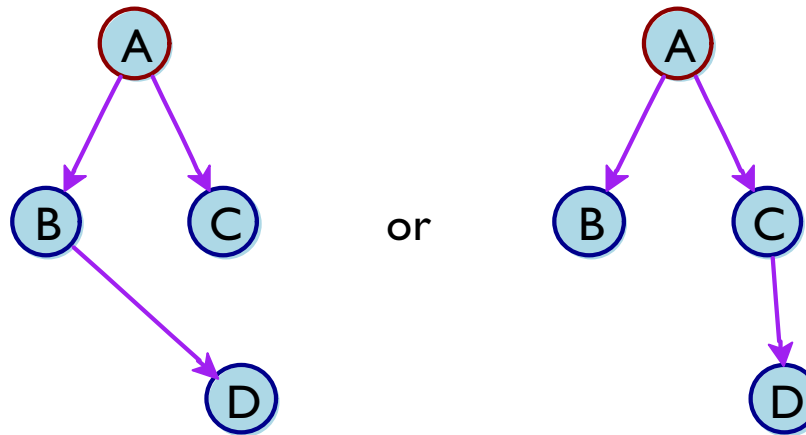
Depth-first:



Designing Programs: Graphs

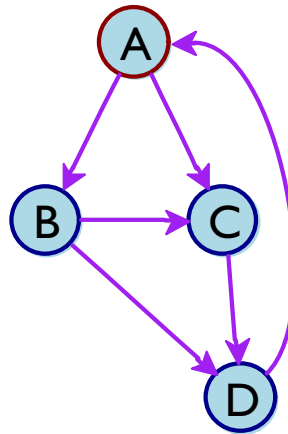


Breadth-first:

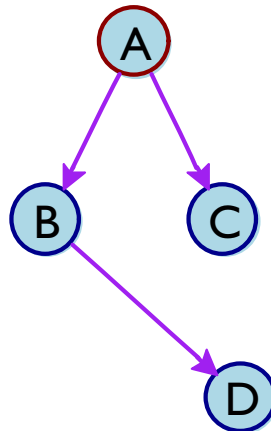


Classical Graph Algorithm

Find the shortest path to a node:

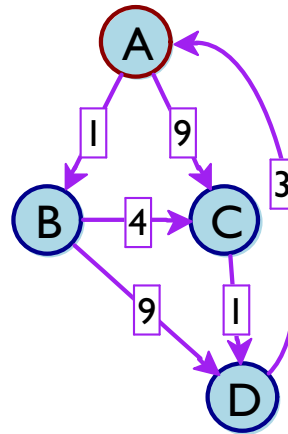


Solution: breadth-first search

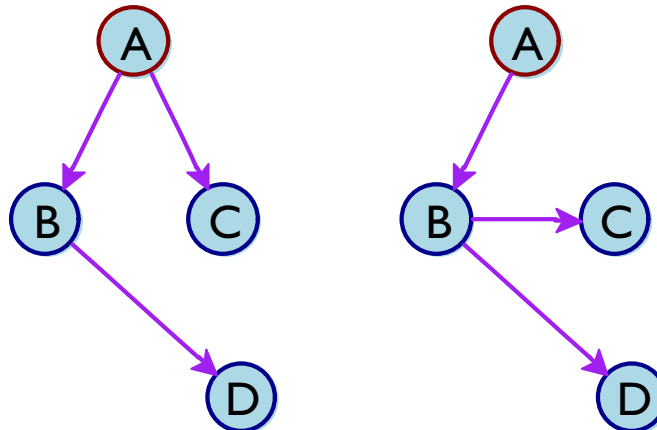


Classical Graph Algorithm

Find the shortest weighted path to a node:

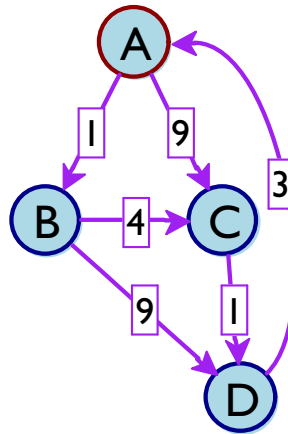


Neither breadth-first nor depth-first works



Classical Graph Algorithm

Find the shortest weighted path to a node:



Solution: use a **priority queue**

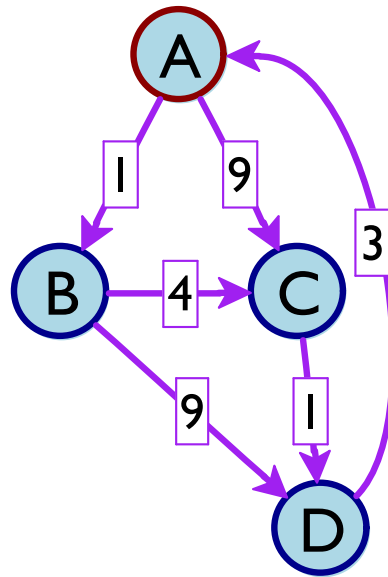
- Enqueue node with distance so far
- Dequeue node that has shortest distance so far

A priority queue gives us “closest-first”

- Instead of a queue (breadth-first)
- Instead of a stack (depth-first)

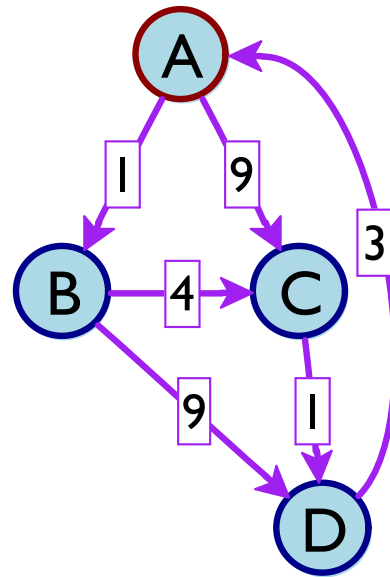
Shortest Weighted Path

0



Shortest Weighted Path

0

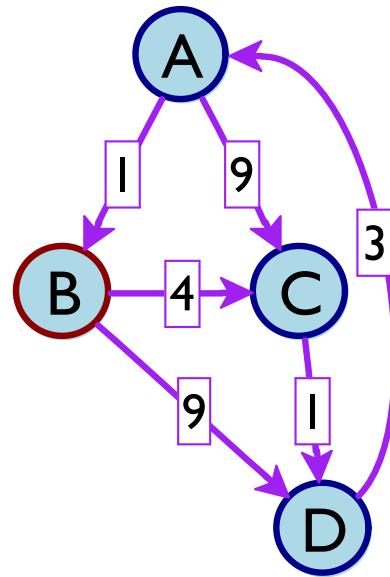


B 1

C 9

Shortest Weighted Path

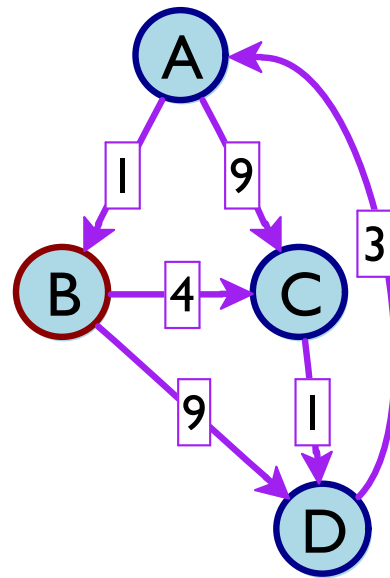
1



C 9

Shortest Weighted Path

1



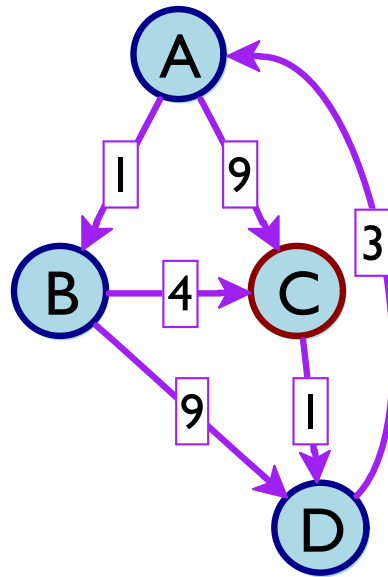
C 5

C 9

D 10

Shortest Weighted Path

5

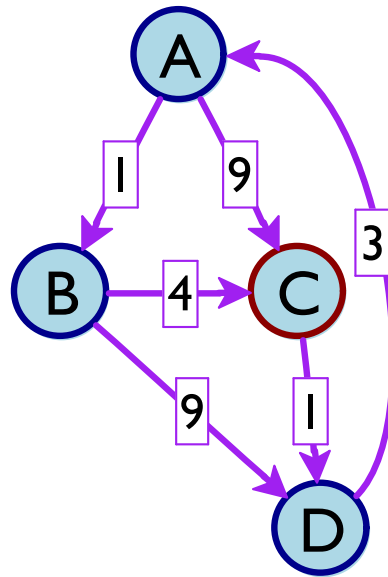


C 9

D 10

Shortest Weighted Path

5



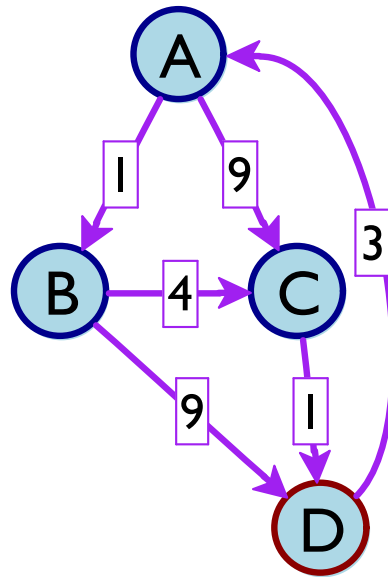
D 6

C 9

D 10

Shortest Weighted Path

6



C 9

D 10

Tracking Seen Nodes

Two common ways to track “already seen” nodes:

- Reserve space in the node for a mutable boolean
 - + Easy to implement (in C)
 - Easy to pollute state
- Use a container
 - More work to implement (in C)
 - + Avoids extra state